Software License Statements

Discovery

Smart Assistant System SAS-M10

This product uses a Linux¹ based operating system based on the Yocto² tool chain. As many of the tools within this OS are distributed under the GPL, you can obtain a copy of the tool chain and sources for the firmware image on request under the following address:

Hoya Corporation – Pentax Medical Division **Digital Endoscopy GmbH**Paul-Lenz-Str. 5

86316 Friedberg – Germany

<u>LinuxLicenceInformation@digitalendoscopy.de</u>

The proprietary software that runs under this operating system and is not publicly available also uses some external open source projects. The dynamically linked libraries are part of the firmware image you can obtain on request as mentioned above.

In detail the following libraries are used:

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1. Statically linked libraries

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https://www.boost.org/

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http://caffe.berkeleyvision.org/

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Our home page can be found at

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http://www.libpng.org

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http://rapidjson.org

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http://rapidxml.sourceforge.net

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1.7 Salite3

https://sqlite.org

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1.8 zlib

www.zlib.net

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Jean-loup Gailly Mark Adler

jloup@gzip.org madler@alumni.caltech.edu

2 Dynamically linked libraries

The following libraries are loading during runtime (dynamically linked)

2.1 Advanced Linux Sound Architecture (ALSA)

https://www.alsa-project.org

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2.2 CUDA Toolkit

https://developer.nvidia.com/cuda-toolkit

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2.3 gflags

https://github.com/gflags/gflags

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2.4 glog

https://github.com/google/glog

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2.6 Mesa 3D Graphics Library

https://mesa3d.org/

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2.11 glibc

https://www.gnu.org/software/libc/

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2.12 libdrm

https://gitlab.freedesktop.org/drm

```
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2.14 libexpat

https://github.com/libexpat/libexpat

```
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https://github.com/systemd/systemd/tree/master/src/libudev

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2.18 libwebp

https://developers.google.com/speed/webp/

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4.4 The GCC Runtime Library Exception

GCC RUNTIME LIBRARY EXCEPTION

Version 3.1, 31 March 2009

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